

MarSurf

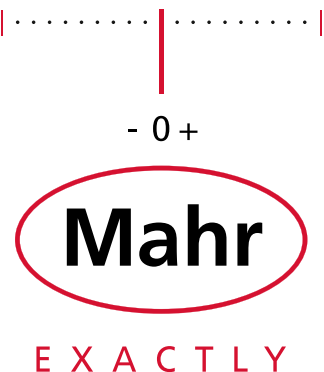


MarSurf LD 130 / 260 Aspheric

**HIGH-PRECISION 2D/3D MEASURING STATION FOR
MEASUREMENT AND EVALUATION OF OPTICAL
COMPONENTS**

- Measuring range 130 mm or 260 mm
- High measuring speed
- Chip-coded innovative probe arms

This is what we mean by EXACTLY.

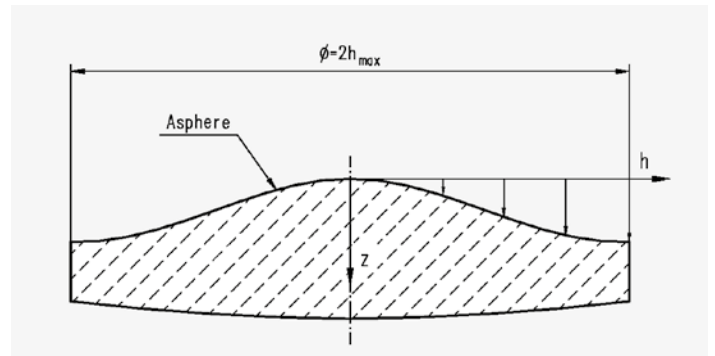


ASPHERE - DEFINITION

An aspherical surface is a refracting or reflecting surface which deviates from a spherical surface. The mathematical description of the sagitta Z (dependence of the vertical height to the horizontal coordinates) of aspherical surfaces based on a conical section is given in the following equation:

$$z(h) = \frac{\frac{h^2}{R_0}}{1 + \sqrt{1 - (1+k) \cdot \left(\frac{h}{R_0}\right)^2}} + \sum_{n=1}^m A_n \cdot h^n$$

- R_0 = Radius of curvature
- h = Radius of interest
- k = Conic constant
- A_n = Aspherical coefficients



More info and videos.

www.mahr.com Webcode 21880

DESCRIPTION

An increasingly more compact and favorable system design is demanded on optical systems such as zoom lenses, optics for DVD drives and lenses in cameras of mobile phones, for example. For this purpose, in addition to classic spherical lens shapes, the optics industry is increasingly producing aspherical (not sphere-shaped) lenses. The evaluation program serves to analyze measurements on aspherical surfaces with Mahr contour measuring units. Measured profiles are imported, the nominal form of the aspheres are defined and the residual error is determined compared to the nominal form. The data of the determined differential profile is made available in a machine-readable format for correction of the processing machine (closed loop). In comparison to a laser interferometer, the tactile measuring technology also allows 2D and 3D measurement of optically rough surfaces, so that testing and correction is already possible in the beginning of the production process (grinding).



APPLICATIONS IN OPTICAL INDUSTRY

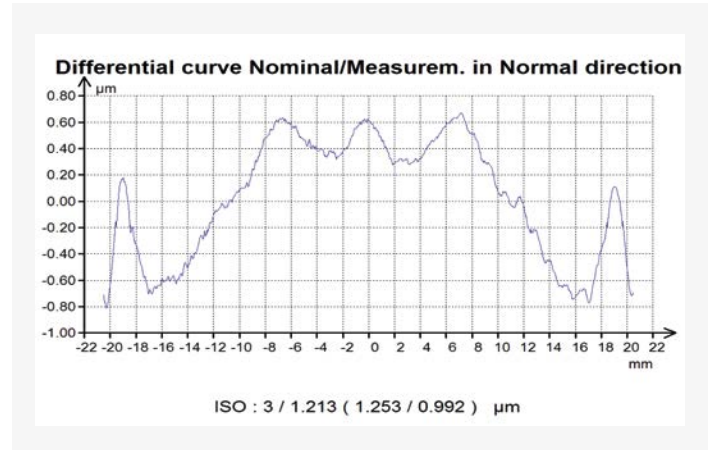
Contour and roughness measurement of:

- spherical and aspherical lenses
- cylinder lenses
- lens mounts
- housing and other mechanical components



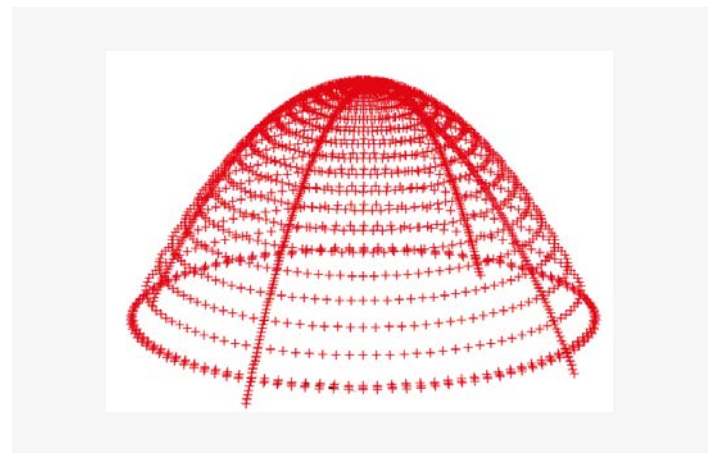
2D MEASUREMENT

- For the 2D measurement, a linear scan over the zenith of the asphere is performed
- Data collection of the aspherical contour
- Comparison of the nominal contour with the measured data
- Results according to DIN ISO 10110-5 (e.g. PV, RMS, slope error)
- Export of the differential profile to manufacturing machines (closed loop)



3D MEASURING PRINCIPLE

For a 3D measurement, two 90° offset linear profiles are first measured across the zenith of the asphere. Second, several concentric circular profiles are gathered by rotating the C-axis. These measured points are used to create the topography. Since the probe arms can be positioned automatically, it is possible to measure discontinuous surfaces such as optics with a hole in the center, for example. The use of the machine in a vibration-damped cabinet keeps ambient influences such as vibrations and impurities away from the measuring object.



3D MEASUREMENT

Before starting the measurement, the nominal form type and set of parameters of the expected nominal asphere are selected. In the next step, the measuring data is recorded and compared to the defined nominal asphere. Results such as RMS value, PV value, and slope error are shown according to DIN ISO 10110-5.

In the software, the individual parameters such as the radius of curvature $R0$, conic constant k and the aspherical coefficients Ai can be adjusted to the measuring values when fitting the nominal asphere into the fit asphere.

In addition to spheres and aspheres, other rotationally symmetric objects can be measured and analyzed. For the nominal shape, several equations and a 2D or 3D point cloud can be used. The 2D scans and the topography can be exported for corrections in production machines.

The differential profile between the determined measuring values and the nominal asphere is shown as a color-coded height picture.

Mahr MarWin 9.00-23	Mahr GmbH Asphere measurement Differential profile & surface parameters	17.05.2017 1 09:12:56 Inspector: Administrator Signature: LD 260 - 113916
Part: Reference Asphere A45-32	Drawing no.: Polishing	Measuring operation: Polishing
Probe arm LP D 14-10-500 1481	Measuring force 5.0 mN	
#13009		
Comments		

Number of circular profiles: 20	Median filter X 1.00 mm Y 1.00 mm																																																							
Differential curve Nominal / Measurement in Normal direction		Results																																																						
		<table border="1"> <tr><th></th><th>µm</th><th>λ</th></tr> <tr><td>PV (W/D)</td><td>1.588</td><td>2.908</td></tr> <tr><td>A PV (W/S)</td><td>0.979</td><td>1.793</td></tr> <tr><td>B PV (W/I)</td><td>1.169</td><td>2.141</td></tr> <tr><td>C PV (W/R)</td><td>0.808</td><td>1.477</td></tr> <tr><td>RMSr</td><td>0.397</td><td>0.726</td></tr> <tr><td>RMSi</td><td>0.275</td><td>0.503</td></tr> <tr><td>RMSa</td><td>0.102</td><td>0.186</td></tr> </table>		µm	λ	PV (W/D)	1.588	2.908	A PV (W/S)	0.979	1.793	B PV (W/I)	1.169	2.141	C PV (W/R)	0.808	1.477	RMSr	0.397	0.726	RMSi	0.275	0.503	RMSa	0.102	0.186																														
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C:/Asphere/v3.65-04/A45-32/1/ λ_{0.85} = 548.07 nm - Mercury (e-line)
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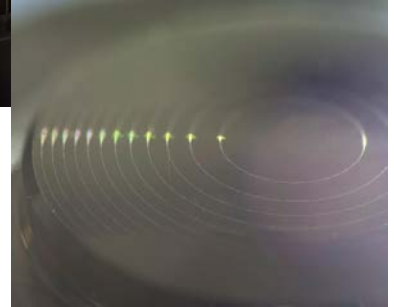
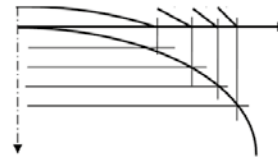
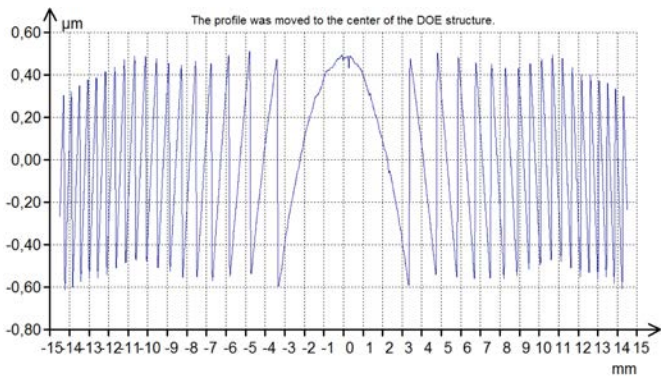
MEASUREMENT OF DIFFRACTIVE OPTICS

Description

- Analysis with constant zone width or constant zone height
- Analysis and subtraction of the base shape (aspherical, spherical, plane)
- Output parameters with tolerances for each zone: angle, zone height, form deviation and much more
- Profile export for machine correction



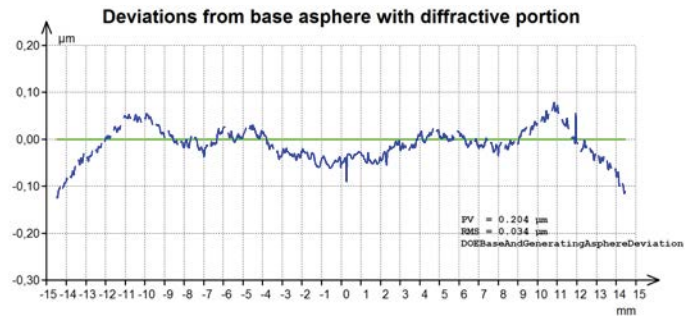
Diffractive structure with base shape removed



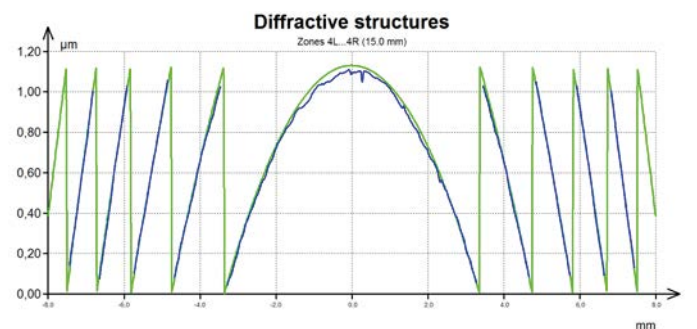
Detailed evaluation of each zone with tolerances (e.g. zone height)

MarWin 9.00-21		Mahr GmbH Asphere measurement Diffractive structures		05.05.2017 3 15:40:56 Inspector: Administrator Signature:		
Part: Reference DOE		Drawing no.: Machining operation:		LD 260 - 116215		
Probe arm LP R 21-10-5_47 1123		Measuring force 0.5 mN				
Comment:						
Heights	Icons	Nominal size (μm)	UT (μm)	LT (μm)	Actual size (μm)	Deviation (μm)
ZONE_0_R_3.3...3.3		1.130	0.200	-0.200	1.131	0.001
ZONE_11_R_4.7...4.7		1.130	0.200	-0.200	1.124	-0.006
ZONE_1R_R_3.5...4.7		1.130	0.200	-0.200	1.130	-0.000
ZONE_21_R_4.5...4.9		1.130	0.200	-0.200	1.157	0.027
ZONE_2R_R_4.5...5.7		1.130	0.200	-0.200	1.137	0.007
ZONE_31_R_6.6...5.9		1.130	0.200	-0.200	1.141	0.011
ZONE_3R_R_5.9...6.6		1.130	0.200	-0.200	1.126	-0.004
ZONE_41_R_7.4...6.8		1.130	0.200	-0.200	1.192	0.061
ZONE_4R_R_6.8...7.4		1.130	0.200	-0.200	1.174	0.044
ZONE_51_R_8.2...7.6		1.130	0.200	-0.200	1.085	-0.045
ZONE_5R_R_7.6...8.2		1.130	0.200	-0.200	1.122	-0.009
ZONE_61_R_8.8...8.3		1.130	0.200	-0.200	1.076	-0.054
ZONE_6R_R_8.3...8.8		1.130	0.200	-0.200	1.102	-0.028
ZONE_71_R_9.4...8.9		1.130	0.200	-0.200	1.127	-0.004
ZONE_7R_R_8.9...9.4		1.130	0.200	-0.200	1.049	-0.081
ZONE_81_R_10.0...9.6		1.130	0.200	-0.200	1.047	-0.084
ZONE_8R_R_9.6...10.0		1.130	0.200	-0.200	1.075	-0.056
ZONE_91_R_10.6...10.2		1.130	0.200	-0.200	1.155	0.025
ZONE_9R_R_10.2...10.6		1.130	0.200	-0.200	1.049	-0.081
ZONE_101_R_11.1...10		1.130	0.200	-0.200	1.098	-0.033
ZONE_10R_R_10.7...11.1		1.130	0.200	-0.200	1.144	0.014
ZONE_111_R_11.6...11		1.130	0.200	-0.200	1.180	0.049
ZONE_11R_R_11.2...11.6		1.130	0.200	-0.200	1.290	0.160
ZONE_121_R_12.0...11		1.130	0.200	-0.200	1.246	0.116
ZONE_12R_R_11.7...12.0		1.130	0.200	-0.200	1.391	0.261
ZONE_131_R_12.5...12		1.130	0.200	-0.200	1.189	0.059
ZONE_13R_R_12.2...12.5		1.130	0.200	-0.200	1.178	0.048

Profile for machine correcting



Detailed view



ADVANTAGES

Checking topography during the first machining operations

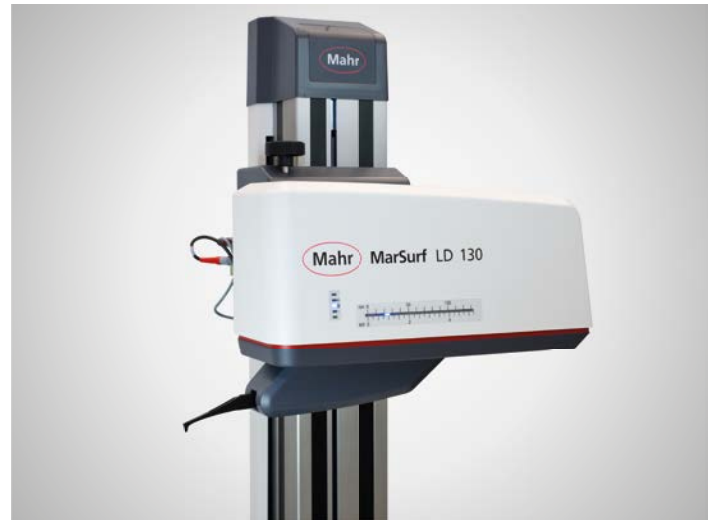
- Early recognition of deviations - saves time-consuming corrections
- Output of differential profile in a machine-readable format for control of the processing machine (closed loop)

Increased flexibility

- Rotational-symmetric objects like spheres, aspheres, conics, etc. can be measured with one measuring system. No additional investments are necessary.
- Large measuring range up to 260 mm
- High measuring speed and dynamics (up to 10 mm/s for large lenses / down to 0.02 mm/s for micro lenses)
- Probe tip can be positioned automatically

Probe arm LP D with innovative design

- Higher dynamics due to increased stiffness, damping and lower moment of inertia:
 - Optimized mechanical design
 - Innovative material selection
- Probe arm with integrated chip:
 - Detection and identification of the probe arm
 - Verification of the correct mounting position
 - Probe arm provides its parameters directly



Your results are correct

- The highly precise MarSurf LD 130 / 260 is the basis for precision measurements of your workpieces. The vertical resolution of 0.8 nm (0.03 μm) and form deviations of less than 100 nm (4 μm) guarantee an exact production of your aspheres.
- Probe arm change without new calibration
- Measurement of steep sided aspheres possible

CALIBRATION SET FOR FIXTURE DIAMETER 25 MM

Consisting of:

- 2 cylinder for set up
- Calibration sphere
- Optical flat

Calibration Set for:

- Stylus calibration and system test
- System adjustment, cylinder with centered ball for chuck adjustment and stylus centering
- Application with automatic calibration and adjustment programs



SOFTWARE SOLUTION: ASPHERIC.LIB

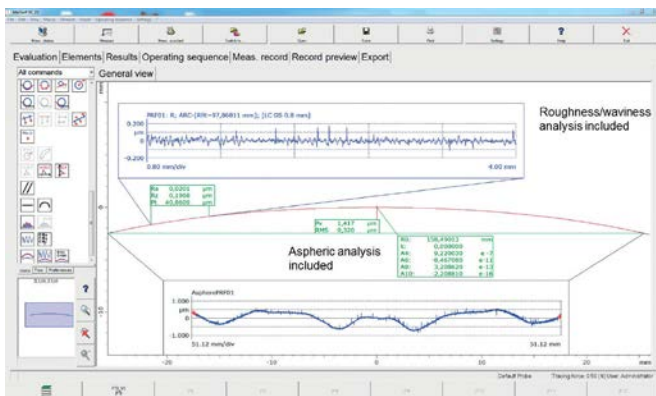
- Analysis of form and contour errors of 2D or 3D measurements, including parameters according to DIN ISO 101105-5
- Automatic PDF record, including evaluation parameters and profiles
- System adjustment
- Automatic measurement
- Fit measured profile to design data (2D and 3D), best-fit radius, sag table
- Derive aspheric coefficients
- Profile export for machine correction (*.txt, *.mod, *.xyz, *.dat, *.ascii, *.x3p)

Option: Diffractive optiale Elements

- Analysis with constant zone width or constant zone height
- Analysis of the base shape (aspherical, spherical, plane)
- Detailed analysis of the diffractive zones
- Differential form error analysis
- Output parameters with tolerances (errors) for each zone: angle zone height, form deviation, zone half diameter
- Profile export for machine correction

MARWIN EASYCONTOUR WITH OPTIONS

- Asphere measurments included
- Roughness and waviness analysis
- Profile analysis
- Parameters with tolerances



Automatic start and end point adjustment, full automation possible

Mahr

Export 2D: *.mod, *.txt, *.ascii, *.x3p
Export 3D: *.dat, *.x3p, *.xyz, *.txt, *.ascii

3D evaluation as per DIN ISO

FWI	µm	λ
B	1.169	2.141
RMSi	0.275	0.503

$$z(h) = \frac{h^2}{4R} + \sum_{n=2}^{\infty} A_{2n} h^{2n}$$

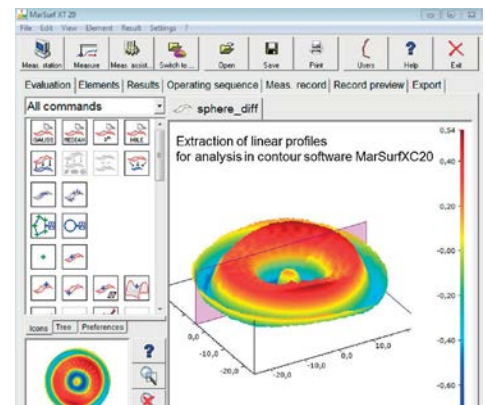
Polynomial degree: 16

Order	Value	Unit
R0	24.88	mm
K	1.0	
A2	0.0	
A4	1.02309e-06	
A6	1.79870733e-10	
A8	6.04983803e-13	
A10	1.35104241e-15	
A12	5.37102042e-19	
A14	1.69403003e-21	
A16	6.714944622e-25	

Aspheric.lib - Aspheric measuring and analysis software

OPTION TOPOGRAPHY

- Measurement and evaluation of 3D surface parameters
- Extraction of linear profiles for evaluation in the MarWin EasyContour software.



TECHNICAL DATA

Properties of the horizontal axis X

Traversing length	0.1 mm up to 130 mm / 260 mm
Positioning speed	0.02 mm/s up to 200 mm/s
Measuring speed	0.02 mm/s to 10 mm/s for roughness measurement recommended: 0.1 mm/s to 0.5 mm/s
Measuring point spacing	0.05 µm up to 30 µm, adjustable
Max number of points in one scan	2.6 million points (MarSurf LD 130) / 5.2 million points (MarSurf LD 260)
Resolution	0.8 nm (0.03 µin)
Uncertainty X-axis display	$\pm (0.2+I/1000) \mu\text{m}$; I in mm
System noise	< 5 nm RMS
Surface roughness	< 5 nm

Technical data probe system (Measuring direction Z+ / Z-)

Probe measuring range	13 mm (100 mm probe arm) 26 mm (200 mm probe arm)
Resolution	0.8 nm
Measuring force	0.5 mN up to 30 mN (electronically adjustable)

Contour - display deviation

Distance measurement EA	MPEEA = $\pm (1.0+I/150)\mu\text{m}$, I in mm
Radius measurement R_K	
R < 10 mm	MPE _R = $\pm 1.0 \mu\text{m}$
10 mm < R < 300 mm	MPE _R = $\pm (0.17+R/12) \mu\text{m}$
R > 300 mm	MPE _R = $\pm (-18+R/7) \mu\text{m}$
Form error	$\leq 100 \text{ nm (2D)*}$ $\leq 200 \text{ nm (3D)*}$
Slope	< $\pm 45^\circ$

* determined at R 22.5 mm calibration ball

Real 3D Measurement

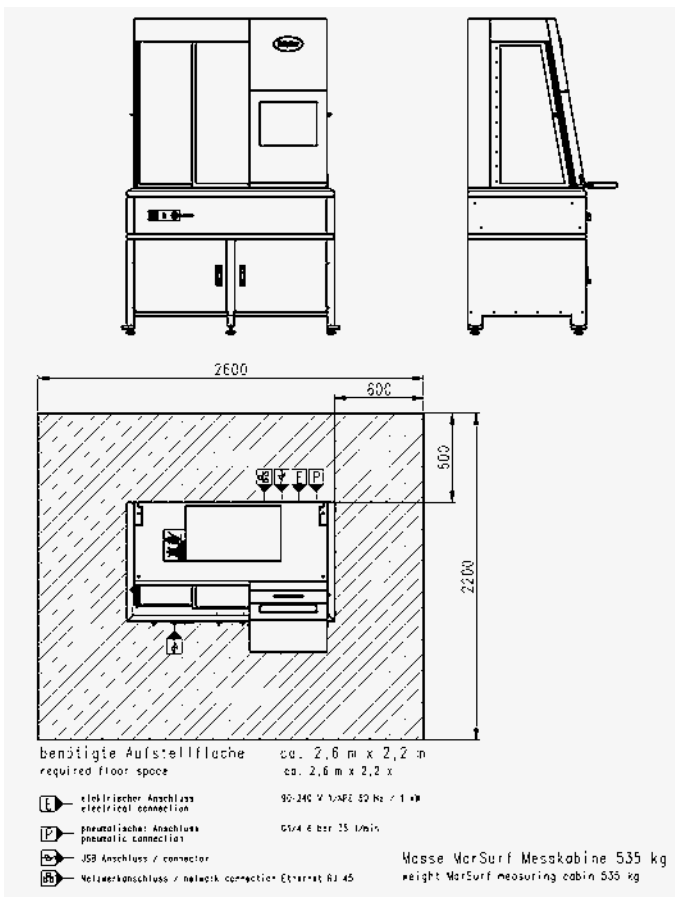
Measuring time	typically 5 to 10 min
Point density	typically: 1 µm linear, 0.1° polar 3D: Number of polar traces + interpolation
Drive unit with automatic y-axis for centering	

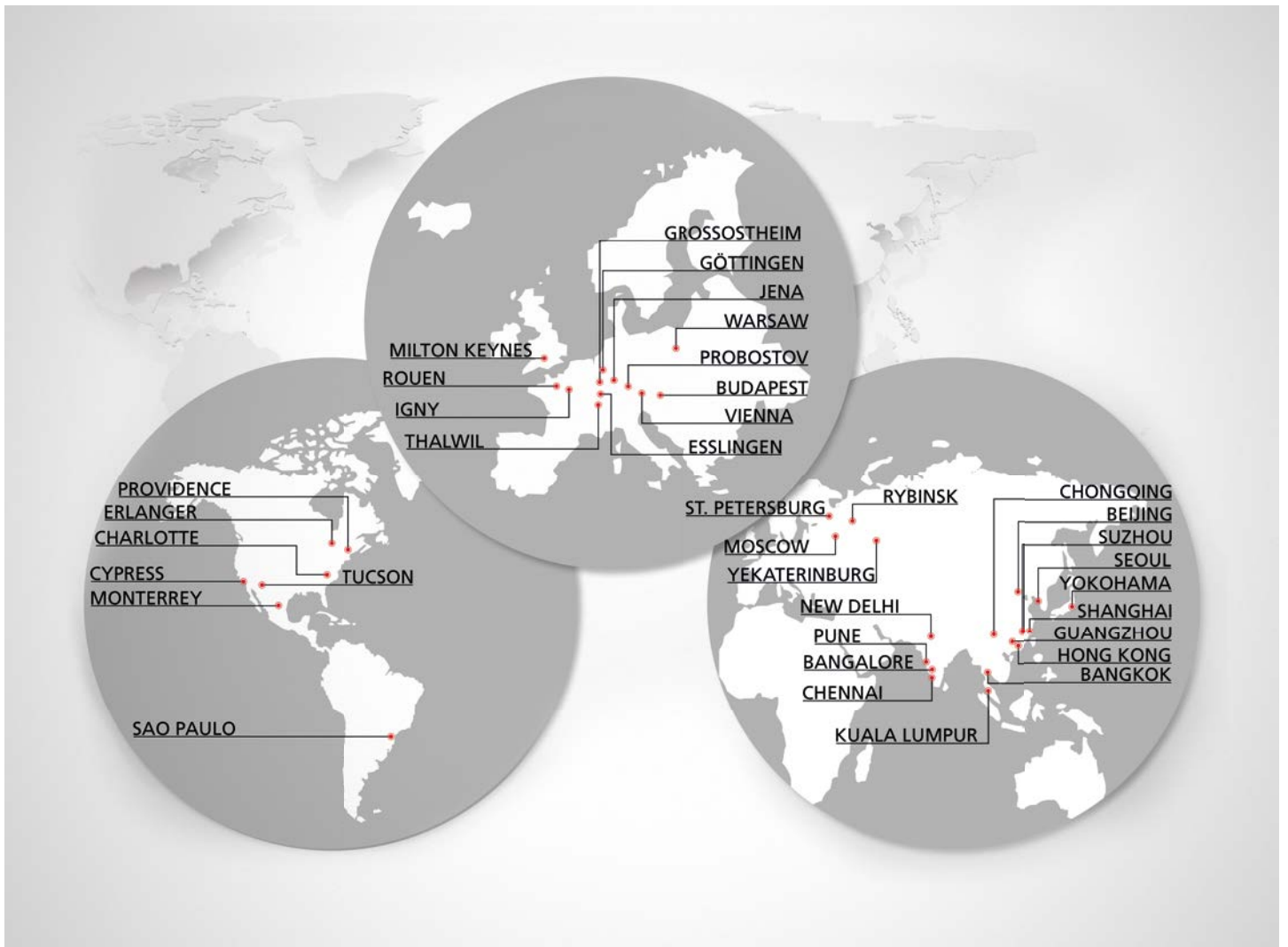
General Data

Operating temperature	+ 15°C to + 35°C
Suggested working temperature	20°C \pm 2K
Temperature change	< 0.5 K/h
Active antivibration system	

High precision spindle (3D version)

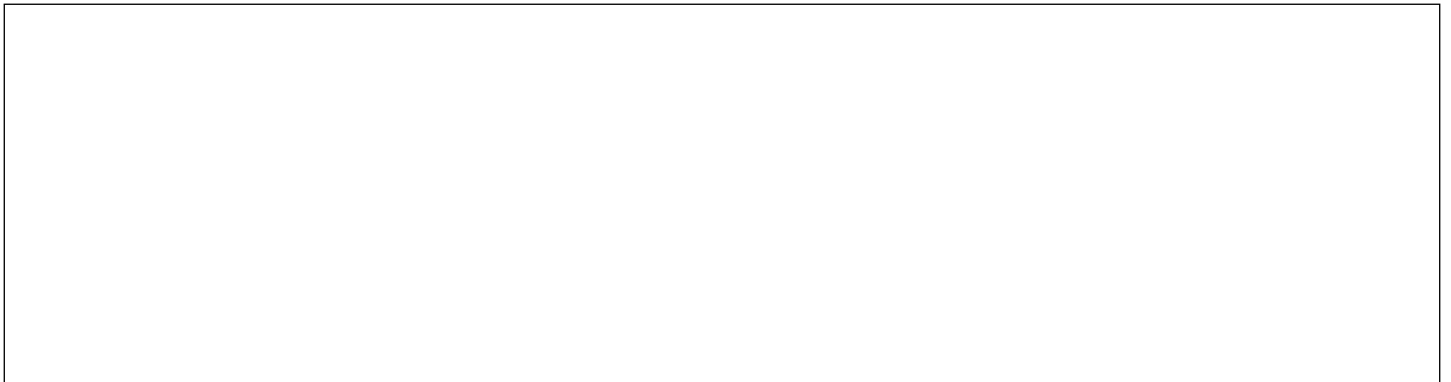
Radial error limit	$\pm (0.01 + 0.00025H) \mu\text{m}$; H = height above table
Axial error limit	$\pm (0.02 + 0.0001R) \mu\text{m}$; R = radius form center
Resolution	0.00025°
Positioning control	< $\pm 0.02^\circ$
Accuracy precision centering	< 0.8 µm
Accuracy precision levelling	< 0.006°





Partner of manufacturing companies worldwide.

Close to our customers.



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EXACTLY